

Probability theory is the mathematical field concerned with *quantifying the likelihood* of uncertain events.

- The *probability of an event* is a number between 0 and 1.
- The closer the number is to 1, the more certain we are that the event will occur.
- The closer the number is to 0, the more certain we are that the event will *not* occur.
- Events whose probabilities are close to  $1/2$  are those about which we are the most *uncertain*.
- The probability of an event depends on what we know (or assume). As the information changes, so can the probability.

## The *frequentist* definition

*The probability of an event is the **relative frequency** with which the event will be observed if the same set of circumstances are repeated a large number of times. I.e., if the event  $E$  is observed  $k$  times in  $n$  repetitions, then the probability of  $E$ , denoted by  $P(E)$ , is  $k/n$ .*

## The *classical* definition

*If a process has  $n$  **equally likely** outcomes and the event  $E$  comprises  $k$  of these outcomes, then  $P(E) = k/n$ .*

**The frequentist and classical definitions are connected by...**

## The *law of large numbers*

*If  $P(E)$  is the (classical) probability of the event  $E$ , then as the number  $n$  of (independent) repetitions of the process grows large, the relative frequency with which  $E$  is observed gets closer and closer to  $P(E)$  (almost certainly).*

**Example.**

Suppose that a fair coin is tossed three times. The (eight) possible outcomes are

*HHH, HHT, HTH, THH, TTH, THT, HTT, TTT*

Unless we have information to the contrary, the only reasonable assumption is that these eight outcomes are equally likely.<sup>a</sup>

If  $E$  is the event “*exactly two H are observed in three tosses*”, then  $E$  is comprised of the outcomes *HHT, HTH* and *THH*, so

$$P(E) = \frac{\# \text{ of outcomes in } E}{\text{total } \# \text{ of outcomes}} = \frac{3}{8}.$$

The *law of large numbers* says in this case that if the process of tossing a coin three times is repeated a large number of times, then ***it is almost certain that*** the relative frequency of the event  $E$  (two  $H$  and one  $T$ ) in this large number of repetitions ***will be very close to***  $3/8$ .

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<sup>a</sup>An instance of Laplace’s *principle of insufficient reason*.

## Conditional probability

(\*) The probability of an event depends on what we know (or assume). As the information changes, so can the probability.

(\*) Suppose that  $E$  and  $F$  are two related events. The *conditional probability* of  $E$  given  $F$ , written  $P(E|F)$ , is the probability of observing event  $E$ , assuming that event  $F$  has been observed.

(\*) If we know that the event  $F$  has occurred, then the set of possible outcomes has changed to include *only those* which occur in  $F$ .

(\*) If  $P(E|F) = P(E)$ , i.e., if observing the event  $F$  does not change the probability of the event  $E$ , then we say that  $E$  and  $F$  are *statistically independent* (or just independent, for short).

**Example.** Returning to the three coin tosses, suppose that  $F$  is the event “*The first coin flip results in H*”, and  $E$  is as before (2H and 1T). If we know that  $F$  has occurred, then the set of possible outcomes is reduced to  $HHH, HHT, HTH$  and  $HTT$ . Two of these four outcomes result in  $E$ , so

$$P(E|F) = \frac{\# \text{ of outcomes in } E \text{ and in } F}{\# \text{ of outcomes in } F} = \frac{2}{4} = \frac{1}{2}.$$

Similarly, if we know that  $E$  has occurred, then the conditional probability of  $F$  given  $E$  is

$$P(F|E) = \frac{\# \text{ of outcomes in } E \text{ and in } F}{\% \text{ of outcomes in } E} = \frac{2}{3},$$

which is different (bigger) than the *unconditional* (or *prior*) probability of  $F$ ,

$$P(F) = \frac{\# \text{ of outcomes in } F}{\text{total } \# \text{ of outcomes}} = \frac{4}{8} = \frac{1}{2}.$$

Looking at either case, we see that  $E$  and  $F$  are *dependent* (not *independent*).

## Rules for calculating probabilities.

1. If the event  $E$  is certain *not* to occur, then  $P(E) = 0$ ; if the event  $E$  is certain *to* occur, then  $P(E) = 1$  and in any case  $0 \leq P(E) \leq 1$ .
2. The conditional probability of  $E$  given  $F$  is calculated as follows:

$$P(E|F) = \frac{P(E \text{ and } F)}{P(F)},$$

where “ $E$  and  $F$ ” is the event where both  $E$  and  $F$  occur. Likewise,

$$P(E|F) = \frac{P(E \text{ and } F)}{P(E)}.$$

In many cases, the conditional probability is known, and we use the formula(s) above to find the probability of “ $E$  and  $F$ ”:

$$P(E \text{ and } F) = P(E) \cdot P(F|E) = P(F) \cdot P(E|F).$$

This is called the *multiplication rule*. In the special case where  $E$  and  $F$  are *independent*, the multiplication rule gives

$$P(E \text{ and } F) = P(E)P(F).$$

3. The probability of “ $E$  or  $F$ ” is given by

$$P(E \text{ or } F) = P(E) + P(F) - P(E \text{ and } F).$$

This is called the *addition rule*.

(\*) If  $P(E \text{ and } F) = 0$ , the events  $E$  and  $F$  are called *mutually exclusive*. If  $E$  and  $F$  are mutually exclusive, then the addition rule simplifies to

$$P(E \text{ or } F) = P(E) + P(F).$$

(\*) The event “ $E$  does **not** occur” (called the *complement* of  $E$ ) is denoted by  $\bar{E}$ . Since it is certain that  $E$  either occurs or does not, and since  $E$  and  $\bar{E}$  are mutually exclusive, the addition rule says

$$P(E) + P(\bar{E}) = P(E \text{ or } \bar{E}) = 1$$

which we often use to find  $P(E) \implies P(E) = 1 - P(\bar{E})$ .

(\*) More generally if  $A$  and  $E$  are any events, then first of all,

$$A = (A \text{ and } E) \text{ or } (A \text{ and } \bar{E})$$

and second, the events  $(A \text{ and } E)$  and  $(A \text{ and } \bar{E})$  are mutually exclusive, so

$$P(A) = P(A \text{ and } E) + P(A \text{ and } \bar{E}).$$

Combining this with the multiplication rule we have the useful formula

$$P(A) = P(E)P(A|E) + P(\bar{E})P(A|\bar{E}).$$

4. **Bayes' rule.** Suppose that we know  $P(B|A)$ , how can we find  $P(A|B)$ ? This question arises in situations where the natural sequence of events is *first*  $A$ , *then*  $B$ . In these situations we often know (or think we know) the *prior* (unconditional) probability  $P(A)$ , as well as the conditional probabilities  $P(B|A)$  and  $P(B|\bar{A})$ . If all of this is known, then

$$P(A|B) = \frac{P(A \text{ and } B)}{P(B)} = \frac{P(A)P(B|A)}{P(A)P(B|A) + P(\bar{A})P(B|\bar{A})}$$



**Example.** Suppose that a test for a certain dread disease (dd) has a probability of 0.02 of returning a *false positive* and a probability of 0.001 of returning a *false negative*. Furthermore, suppose that it is known that 1% of the population is infected with dd.

**Question:** If a random individual tests positive for dd, what is the probability that he or she is actually infected?

**Answer:** First, some notation. I'll use  $D$  to denote the event that the individual is infected with dd and  $T$  for the event that the individual tests positive for dd.

What we know is (i)  $P(D) = 0.01$  (probability that a randomly individual is infected), (ii)  $P(T|\bar{D}) = 0.02$  (probability of a false positive) and (iii)  $P(\bar{T}|D) = 0.001$  (probability of a false negative). What we want to know is  $P(D|T)$ , and we can use Bayes' rule to find it.

First,  $P(\bar{D}) = 1 - P(D) = 0.99$ . Likewise

$$P(T|D) = 1 - P(\bar{T}|D) = 1 - 0.001 = 0.999$$

(conditional probabilities behave exactly like unconditional probabilities).

Now we can simply plug everything into Bayes' formula

$$\begin{aligned} P(D|T) &= \frac{P(T \text{ and } D)}{P(T)} \\ &= \frac{P(D)P(T|D)}{P(D)P(T|D) + P(\bar{D})P(T|\bar{D})} \\ &= \frac{(0.01)(0.999)}{(0.01)(0.999) + (0.99)(0.02)} = \frac{0.00999}{0.02979} \approx 0.335. \end{aligned}$$

**Conclusion:** Even though there is a very low probability of a false positive, a positive test result indicates an infected person in only about 1 out of 3 cases. This may appear contradictory at first, but you have to remember that a false positive is the conditional event “*positive result given no infection*” ( $T|\bar{D}$ ), while the event whose probability we just calculated is “*infection given positive test*” ( $D|T$ ).

In this example the probability  $P(D|T)$  is relatively low because of the *prior* probability  $P(D) = 0.01$ . Most people are not infected, so even though very few of them test positive, almost two thirds of all positive results (in this hypothetical example) are false positives.